

# MATHEMATICAL MODELLING OF FINGERO-IMBIBITION PHENOMENON IN HETEROGENEOUS POROUS MEDIUM WITH MAGNETIC FIELD EFFECT

MAHENDRA A. PATEL<sup>1</sup> AND N. B. DESAI<sup>2\*</sup>

<sup>1</sup>Government Engineering College, Gandhinagar-382028, Gujarat (India), E-mail: mahendraapatel@yahoo.co.in. Telephone. +91-9737730526
<sup>2</sup> A. D. Patel Institute of Technology, New V. V. Nagar-388121, Gujarat (India), E-mail: drnbdesai@yahoo.co.in. Telephone. +91-9327158932

# ABSTRACT

The present paper discusses the mathematical model for fingero-imbibition phenomenon arising in fluid flow through the heterogeneous porous medium with magnetic field effect during secondary oil recovery process. The mathematical formulation leads to a nonlinear partial differential equation and its solution has been obtained with appropriate boundary conditions by homotopy analysis method. The solution represents the saturation of injected water for fingero-imbibition phenomenon which increases when distance increases for given time. The graphical and numerical representations of the solution are discussed.

Keywords: Fluid flow, Heterogeneous porous medium, Fingero-imbibition phenomenon, Homotopy analysis method. AMS subject classification: 76S05, 76Txx, 65Nxx, 35Q35.

### **INTRODUCTION**

If a porous medium filled with some phase (oil) is brought into contact with another phase (water) which preferentially wets the medium, there is a spontaneous flow of the wetting phase (water) into the medium and a counter flow of the native phase (oil) from the medium. This phenomenon occurring due to the difference of wetting abilities of the phases is called imbibition phenomenon. Besides this if a porous medium filled with one phase (oil) is displaced by another phase (water) of lesser viscosity, then instead of regular displacement of the whole front, protuberances may occur which shoot through the porous medium at relatively very high speed giving rise to the fingering phenomenon. This simultaneous occurrence of both phenomena fingering and imbibition is known as fingeroimbibition phenomenon (see fig. 1).

The imbibition phenomenon have been investigated by many researches with different aspects. Mishra and Verma [3] have discussed imbibition in the flow of two immiscible fluids (oil and water) with magnetic field. Shah and Verma [5] have obtained the numerical solution of fingero-imbibition phenomenon through homogeneous porous media with magnetic field using finite difference method. Desai [21] has discussed the imbibition phenomenon by similarity transform. Patel, Mehta and Patel [9] have discussed mathematical model of imbibition phenomenon in heterogeneous porous media. Parikh, Mehta and Pradhan [10] have discussed mathematical modeling of fingero-imbibition phenomenon in homogeneous porous medium with magnetic field effect in vertical downward direction. Patel, Rabari and Bhathawala [11] have obtained numerical solution of imbibition phenomenon in a homogeneous medium with magnetic fluid.

In the present work, we have developed the mathematical model for fingero-imbibition



Figure 1: Fingero-imbibition phenomenon.

phenomenon in heterogeneous porous medium with magnetic field effect. The mathematical formulation leads to the governing nonlinear partial differential equation. The solution of the problem have been obtained using homotopy analysis method [20]. The main aim of this work is to find the solution (the saturation of injected water) of the fingero-imbibition phenomenon in the heterogeneous porous medium with magnetic field effect.

#### AIM AND SCOPE OF THE WORK

The aim with this work is to discuss the mathematical model for fingero-imbibition phenomenon arising in fluid flow through the heterogeneous porous medium with magnetic field effect during secondary oil recovery process. The solution of problem is obtain by using homotopy analysis method. This solution represents the saturation of injected water which helps us to predict the amount of water required to inject for recovering oil. This type of mathematical model is useful for predicting oil recovery from petroleum reservoir.

#### STATEMENT OF THE PROBLEM

Here we consider the cylindrical piece of heterogeneous porous matrix of length L which is filled with oil. During the secondary oil recovery process, the imbibition phenomenon will occur simultaneously with fingering which describes the fingero-imbibition phenomenon. It is considered that the flow of water with magnetic particles and oil in the heterogeneous porous medium under the variable magnetic field effect. In this work assumed that the injected water is conductive while the oil is non-conductive and the effect of a variable magnetic field is to increase the velocity of injected water by gradient of  $\frac{\omega H^2}{8\pi}$  where  $\omega$  is permeability of magnetic field *H*. It is assumed that the Darcy's law is valid for the investigated flow system for the mathematical model of the fingero-imbibition phenomenon and the average cross sectional area occupied by the fingers was observed.

The saturation of the injected water  $S_w(x, t)$  is then defined as the average cross-sectional area occupied by injected water at distance x and time t. The porosity and permeability of heterogeneous porous medium may vary from one place to another place. Considered that the porosity and permeability of heterogeneous porous medium are the functions of variable x only.

### MATHEMATICAL MODEL

The velocity of injected water  $V_w$  and velocity of oil  $V_o$  can be represented due to Darcy's law as [14, 15]:

$$V_{w} = -\frac{k_{w}}{\delta_{w}} K \left[ \frac{\partial P_{w}}{\partial x} + \frac{\omega H}{4\pi} \frac{\partial H}{\partial x} \right]$$
(1)

$$V_o = -\frac{k_o}{\delta_o} K \frac{\partial P_o}{\partial x}$$
(2)

where  $V_w$  and  $V_o$  are the velocities of water and oil respectively,  $k_w$  and  $k_o$  are the relative permeabilities of water and oil respectively,  $\delta_w$ and  $\delta_o$  are the constant viscosities of water and oil respectively, *K* is the variable permeability of the heterogeneous porous medium,  $P_w$  and  $P_o$  are the pressures of water and oil respectively,  $\omega$  is permeability of magnetic field *H*.

The equation of continuity of injected water is

$$P\frac{\partial S_w}{\partial t} + \frac{\partial V_w}{\partial x} = 0 \tag{3}$$

where P = P(x) is the variable porosity of the heterogeneous porous medium.

The pressure difference is given by the capillary pressure  $P_c$ :

$$P_c = P_o - P_w \,. \tag{4}$$

The imbibition condition for countercurrent imbibition phenomenon can be expressed as [14]

$$V_w = -V_o \,. \tag{5}$$

Using equations (1), (2) and (4) in (5), we get

$$\frac{\partial P_w}{\partial x} = -\left(\frac{k_w}{\delta_w} + \frac{k_o}{\delta_o}\right)^{-1} \left(\frac{k_o}{\delta_o}\frac{\partial P_c}{\partial x} + \frac{k_w}{\delta_w}\frac{\omega H}{4\pi}\frac{\partial H}{\partial x}\right).$$
 (6)

According to Scheidegger [14], we have

$$\frac{k_w}{\delta_w} \frac{k_o}{\delta_o} \left(\frac{k_w}{\delta_w} + \frac{k_o}{\delta_o}\right)^{-1} \approx \frac{k_o}{\delta_o}.$$
 (7)

On substituting the value of  $\frac{\partial P_W}{\partial x}$  with (7) in equation (1), we get

$$V_{w} = K \frac{k_{o}}{\delta_{o}} \left[ \frac{\partial P_{c}}{\partial x} - \frac{\omega H}{4\pi} \frac{\partial H}{\partial x} \right].$$
(8)

Substituting equation (8) into (3), we get

$$P\frac{\partial S_w}{\partial t} + \frac{\partial}{\partial x} \left[ K\frac{k_o}{\delta_o} \frac{\partial P_c}{\partial x} - K\frac{k_o}{\delta_o} \frac{\omega H}{4\pi} \frac{\partial H}{\partial x} \right] = 0.$$
(9)

# $PRAJ\tilde{N}A$ - Journal of Pure and Applied Sciences Vol. 24 – 25 : 15–22 (2017) ISSN 0975 - 2595

We assume that the capillary pressure  $P_c$  is a continuous linear function of the form [19]

$$P_c = -\beta S_w \tag{10}$$

where  $\beta$  is a constant.

Due to Scheidegger and Johnson [1], we assume the standard relationship between phase saturation and relative permeability as

$$k_w = S_w$$
 and  $k_o = 1 - \alpha S_w$  (11)

where  $\alpha$  is a constant.

For the heterogeneous porous medium, we assume the porosity and permeability as functions of x only [2],

$$P(x) = \frac{1}{a_1 - a_2 x}$$
 and  $K(x) = K_0(1 + bx)$  (12)

where  $a_1$ ,  $a_2$ ,  $K_0$  and b are positive constants. Since P(x) can't exceed unity, we assume that  $a_1 - a_2 x \ge 1$ .

For simplicity, we consider  $K \propto P$  [17],

$$K = K_c P \tag{13}$$

where  $K_c$  is a constant.

Considering the magnetic field in the x-direction only, we write H as [4, 22]

$$H = \lambda x^n \tag{14}$$

where  $\lambda$  is a constant parameter and n is an integer.

Using the value of *H* for n = 1 in equation (9) with equations (13), (11) and (10), we get

$$\frac{\partial S_w}{\partial t} = \frac{\beta K_c}{\delta_o P} \frac{\partial}{\partial x} \left[ P(1 - \alpha S_w) \frac{\partial S_w}{\partial x} \right] + \frac{K_c \omega \lambda^2}{4\pi \delta_o P} \frac{\partial}{\partial x} \left[ P(1 - \alpha S_w) x \right].$$
(15)

Using dimensionless variables

$$X = \frac{x}{L}, \qquad T = \frac{\beta K_c t}{\delta_o L^2},$$

equation (15) becomes,

$$\frac{\partial S_w}{\partial T} = \frac{1}{P} \frac{\partial}{\partial X} \left[ P(1 - \alpha S_w) \frac{\partial S_w}{\partial X} \right] \\ + \frac{\omega \lambda^2 L^2}{4\pi\beta P} \frac{\partial}{\partial X} \left[ P(1 - \alpha S_w) X \right].$$
(16)

Now,

$$\frac{1}{P}\frac{\partial P}{\partial X} = \frac{\partial(\log P)}{\partial X}$$
$$= \frac{\partial}{\partial X} \left(\frac{a_2 L X}{a_1} - \log a_1\right)$$
(neglecting higher order terms of X)
$$= \frac{a_2 L}{a_1}.$$

Equation (16) reduces to

$$\frac{\partial S_{w}}{\partial T} = \frac{\partial}{\partial X} \left[ (1 - \alpha S_{w}) \frac{\partial S_{w}}{\partial X} \right] + A(1 - \alpha S_{w}) \frac{\partial S_{w}}{\partial X} + B \frac{\partial}{\partial X} \left[ (1 - \alpha S_{w}) X \right] + AB(1 - \alpha S_{w}) X$$
(17)

where  $A = \frac{a_2 L}{a_1}$ ,  $B = \frac{\omega \lambda^2 L^2}{4\pi \beta}$  and  $S_w(x,t) = S_w(X,T)$ .

A set of suitable boundary conditions for fingero-imbibition phenomenon are considered as

$$S_w(0,T) = \frac{T}{5} \text{ and } S_w(1,T) = \frac{1+3T}{5}$$
 (18)

The equation (17) is the desired governing nonlinear partial differential equation for the fingero-imbibition phenomenon in the heterogeneous porous medium with magnetic field effect. The solution  $S_w(X,T)$  of equation (17) represents the saturation of injected water at distance X and time T.

#### APPLICATION OF HOMOTOPY ANALYSIS METHOD

In 1992, Liao [20] proposed a new technique homotopy analysis method (HAM) to obtain solutions of nonlinear differential equations. Many authors have applied the HAM for solving ordinary differential equations and partial differential equations. For example, Liao [16] has discussed solution of various ODEs by HAM. Liao [6] has obtained solution for an unsteady boundary-layer flow due to an impulsively stretched sheet by HAM. Ali and Mehmood [7] have discussed the solution of the unsteady boundary layer flow equations by HAM. Darvishi and Khani [8] have applied the HAM to solve the foam drainage equation. Patel and Desai [12, 13, 23] have applied the HAM to one dimensional

# $PRAJ\bar{NA}$ - Journal of Pure and Applied Sciences Vol. 24 – 25 : 15–22 (2017) ISSN 0975 - 2595

partial differential equation arising in fluid flow through porous medium.

Let us consider the nonlinear partial differential equation according to equation (17) as

$$\mathcal{N}[\varphi(X,T;q)] = 0 \tag{19}$$

where  $q \in [0,1]$  is the embedding parameter,  $\varphi(X,T;q)$  is an unknown function and a nonlinear operator  $\mathcal{N}$  is defined as

$$\mathcal{N}[\varphi(X,T;q)] = \frac{\partial^2 \varphi(X,T;q)}{\partial X^2} - \alpha \varphi(X,T;q) \frac{\partial^2 \varphi(X,T;q)}{\partial X^2} - \alpha \left\{ \frac{\partial \varphi(X,T;q)}{\partial X} \right\}^2 + (A - B\alpha X) \frac{\partial \varphi(X,T;q)}{\partial X} - A\alpha \varphi(X,T;q) \frac{\partial \varphi(X,T;q)}{\partial X} - (B\alpha + AB\alpha X) \varphi(X,T;q) + ABX + B - \frac{\partial \varphi(X,T;q)}{\partial T}$$
(20)

According to boundary conditions (18), it is straightforward to choose initial approximation as

$$S_{w_0}(X,T) = \frac{T + X^2 + T(X + X^2)}{5}$$
(21)

Now we choose the linear operator as

$$\mathcal{L}[\varphi(X,T;q)] = \frac{\partial^2 \varphi(X,T;q)}{\partial X^2}$$
(22)

which has the property  $\mathcal{L}(f) = 0$  when f = 0.

Let  $c_0 \neq 0$  be the convergence control parameter and H(X,T) be a non-zero auxiliary function. Liao [20] constructed, the so-called zeroth-order deformation equation

$$(1-q)\mathcal{L}[\varphi(X,T;q) - S_{w_0}(X,T)]$$
  
=  $qc_0H(X,T)\mathcal{N}[\varphi(X,T;q)]$  (23)

where  $S_{w_0}(X,T)$  is an initial approximation of  $S_w(X,T)$ . When q = 0 and q = 1, we have

$$\varphi(X,T;0) = S_{w_0}(X,T) \text{ and } \varphi(X,T;1) = S_w(X,T)$$
(24)

respectively. Therefore, when *q* increases from 0 to 1, the solution  $\varphi(X,T;q)$  deforms (varies) from the initial approximation  $S_{w_0}(X,T)$  to the solution

 $S_w(X,T)$ . By Taylor's theorem, we expand  $\varphi(X,T;q)$  in powers of q as

$$\varphi(X,T;q) = S_{w_0}(X,T) + \sum_{m=1}^{\infty} S_{w_m}(X,T)q^m \quad (25)$$

where

$$S_{w_m}(X,T) = \frac{1}{m!} \frac{\partial^m \varphi(X,T;q)}{\partial q^m} \bigg|_{q=0}.$$
 (26)

Assume that the linear operator, the initial approximation, the convergence control parameter and the auxiliary function are selected such that the series (25) is convergent at q = 1. Then at q = 1, the series (25) becomes

$$S_w(X,T) = S_{w_0}(X,T) + \sum_{m=1}^{\infty} S_{w_m}(X,T)$$
(27)

the

vector

 $\overrightarrow{S_{w_n}} = \{S_{w_0}(X,T), S_{w_1}(X,T), \dots, S_{w_n}(X,T)\}.$ Differentiating (23) *m* times with respect to *q* and then putting *q* = 0 and finally dividing them by

then putting q = 0 and finally dividing them by m!, we have the so-called high-order deformation equation

$$\mathcal{L}\left[S_{w_m}(X,T) - \chi_m S_{w_{m-1}}(X,T)\right] = c_0 H(X,T) \mathcal{R}_m(\overrightarrow{S_{w_{m-1}}})$$
(28)

where

Define

$$\mathcal{R}_{m}(\overrightarrow{S_{w_{m-1}}}) = \frac{\partial^{2} S_{w_{m-1}}}{\partial X^{2}} - \alpha \sum_{j=0}^{m-1} S_{w_{j}} \frac{\partial^{2} S_{w_{m-1-j}}}{\partial X^{2}} - \alpha \sum_{j=0}^{m-1} \frac{\partial S_{w_{j}}}{\partial X} \frac{\partial S_{w_{m-1-j}}}{\partial X} + A \frac{\partial S_{w_{m-1}}}{\partial X} - B\alpha X \frac{\partial S_{w_{m-1}}}{\partial X} - A\alpha \sum_{j=0}^{m-1} S_{w_{j}} \frac{\partial S_{w_{m-1-j}}}{\partial X} - B\alpha S_{w_{m-1}} - AB\alpha X S_{w_{m-1}} + (B + ABX)(1 - \chi_{m}) - \frac{\partial S_{w_{m-1}}}{\partial T}, m \ge 1$$
(29)

and

$$\chi_m = \begin{cases} 0 , & when \quad m \le 1\\ 1 , & when \quad m > 1. \end{cases}$$
(30)

Here we consider the auxiliary function as H(X,T) = 1. Then the equation (28) becomes

# $PRAJ\bar{NA}$ - Journal of Pure and Applied Sciences Vol. 24 – 25 : 15–22 (2017) ISSN 0975 - 2595

$$S_{w_m}(X,T) = \chi_m S_{w_{m-1}}(X,T) + c_0 \mathcal{L}^{-1} \left[ \mathcal{R}_m \left( \overrightarrow{S_{w_{m-1}}} \right) \right] + C_1 X + C_2$$
(31)

where  $C_1$  and  $C_2$  are determined by the boundary conditions  $S_{w_m}(0,T) = 0$  and  $S_{w_m}(1,T) = 0$ ,  $m \ge 1$ . Solution of (31) gives  $S_{w_1}(X,T)$ ,  $S_{w_2}(X,T)$ and so on. Hence the homotopy series solution of (17) is as

$$S_{w}(X,T) = \frac{T + X^{2} + T(X + X^{2})}{5} + c_{0} \left[ -\frac{X}{20} + \frac{X^{2}}{10} - \frac{X^{3}}{30} - \frac{X^{4}}{60} - \frac{TX}{5} + \frac{TX^{2}}{5} - \frac{BX}{2} + \frac{BX^{2}}{2} - \frac{ABX}{60} + \frac{ABX^{3}}{6} + \frac{ABX^{3}}{6} + \frac{A}{5} \left( -\frac{X}{3} + \frac{X^{3}}{3} - \frac{5TX}{6} + \frac{TX^{2}}{2} + \frac{TX^{3}}{3} \right) - \frac{\alpha}{25} \left( -\frac{X}{2} + \frac{X^{4}}{2} - 3TX + TX^{2} + TX^{2} + TX^{3} + TX^{4} - 3T^{2}X + \frac{3T^{2}X^{2}}{2} + T^{2}X^{3} + \frac{T^{2}X^{4}}{2} \right) - \frac{A\alpha}{25} \left( -\frac{X}{10} + \frac{X^{5}}{10} - \frac{47TX}{60} + \frac{TX^{3}}{3} + \frac{TX^{4}}{4} + \frac{TX^{5}}{5} - \frac{27T^{2}X}{20} + \frac{T^{2}X^{2}}{2} + \frac{T^{2}X^{3}}{2} + \frac{T^{2}X^{3}}{2} + \frac{T^{2}X^{4}}{4} + \frac{T^{2}X^{5}}{10} \right) - \frac{B\alpha}{5} \left( -\frac{X}{4} + \frac{X^{4}}{4} - \frac{13TX}{12} + \frac{TX^{2}}{2} + \frac{TX^{3}}{3} + \frac{TX^{4}}{4} \right) - \frac{AB\alpha}{5} \left( -\frac{X}{20} + \frac{X^{5}}{20} - \frac{3TX}{10} + \frac{TX^{3}}{6} + \frac{TX^{4}}{12} + \frac{TX^{5}}{20} \right) \right] + \cdots$$
 (32)

The solution (32) represents the saturation of injected water at distance X and time T for the fingero-imbibition phenomenon arising in fluid flow through the heterogeneous porous medium with magnetic field effect.

As pointed out by Liao, the convergence of the homotopy series solution depends upon the value of convergence control parameter  $c_0$ . The proper value of  $c_0$  has been obtained using  $c_0$ curves. Many authors have discussed the convergence of the homotopy series solution. For example, Liao [6, 16], Ali and Mehmood [7], Darvishi and Khani [8], Patel and Desai [12, 13, 23] have chosen a proper value of  $c_0$  providing us the convergent homotopy series solution of nonlinear ODEs and PDEs. With the help of Mathematica package for nonlinear BVPs [18], the so-called  $c_0$ -curves are plotted for 20th order approximation. This helps us to discover the range for the admissible values of  $c_0$ , which corresponds to the horizontal line segment. It is obvious that the valid domain of  $c_0$  is  $-1.2 \le c_0 \le -0.4$  from the  $c_0$ -curves (see figures 2-4). This means that the series (32) converges for these values of  $c_0$ .



Figure 3: The  $c_0$ -curves of  $S_{w\chi}(0, 0)$  (Solid line),  $S_{w\chi\chi}(0, 0)$  (DotDashed line) and  $S_{w\chi\chi\chi}(0, 0)$  (Dashed line).



### **RESULTS AND DISCUSSION**

The following values of constants are considered as:  $L = 1, \alpha = 1.11, a_1 = 2, a_2 = 1$ ,  $\beta = 0.1$ ,  $\omega = 0.1$ ,  $\lambda = 0.1$  and we choose the proper value of the convergence control parameter  $c_0 = -0.8$  to obtain convergent series solution. We have considered first 20 terms of series solution. Hence it gives an approximate solution of fingero-imbibition phenomenon in heterogeneous porous media with magnetic field effect. Table 1 indicates the numerical values of saturation of injected water for fingeroimbibition phenomenon at distance X for time T. Graphical presentation of the saturation of injected water is obtained by using Mathematica software. The graph of saturation of injected water versus distance X for fixed time T = 0.1, 0.2, ..., 1 is given in fig. 5 and fig. 6 represents the graph of saturation of injected water versus time T for fixed distance  $X = 0.1, 0.2, \dots, 1$ 





## COMPARATIVE STUDY WITH FINGERO-IMBIBITION PHENOMENON IN HETEROGENEOUS POROUS MEDIUM WITHOUT MAGNETIC FIELD EFFECT

Patel and Desai [13] have discussed homotopy series solution for fingero-imbibition phenomenon in heterogeneous porous medium without magnetic field effect. Table 2 shows the comparative numerical values of the saturation of injected water of fingero-imbibition phenomenon without magnetic field effect [13] and with magnetic field effect.

#### CONCLUSION

We have discussed the fingero-imbibition phenomenon in heterogeneous porous medium with magnetic field effect under certain assumptions. The homotopy series solution (32) represents the saturation of injected water. The solution (32) satisfies the boundary conditions (18). Numerical and graphical representations are obtained using Mathematica software. Table 1 indicates the numerical values of the saturation of injected water. Figures 5 and 6 give graphical representation. It is concluded that the saturation injected water of fingero-imbibition of phenomenon increases when the distance increases for given time T. Due to additional magnetic field effect the saturation of injected water is more increasing than the saturation of injected water without magnetic field effect. We can conclude that the magnetic field effect plays an important role in the fingero-imbibition

phenomenon in the heterogeneous porous medium.

#### REFERENCES

- Scheidegger, A. E. and Johnson, E. F., (1961), The statistically behavior of instabilities in displacement process in porous media, Canadian J. Physics, 39 (2), pp. 326-334.
- [2] Verma, A. P., (1969), Statistical behavior of fingering in a displacement process in heterogeneous porous medium with capillary pressure, Canadian J. Physics, 47 (3), pp. 319-324.
- [3] Mishra, S. K. and Verma, A. P., (1974), Imbibition in the flow of two immiscible fluids with magnetic field, The Physics of fluids, American Institute of Physics, 17 (6), pp. 1338-1340.
- [4] Verma, A. P., (1980), Instabilities in two phase flow through porous media with magnetic field, Multiphase transport: Fundamentals, Reactor Safety, Applications (Ed. T. N. Veziroglu), Hemisphere Publication Corporation, Washington, 3, pp. 1323-1335.
- [5] Shah, R. C. and Verma, A. P., (1998), Fingero-imbibition phenomenon through porous media with magnetic field, Indian J. of Engg. and Materials Sciences, 5, pp. 411-415.
- [6] Liao, S. J., (2006), An analytic solution of unsteady boundary-layer flows caused by an impulsively stretching plate, Commun. Nonlinear Sci. Numer. Simul., 11 (3), pp. 326-339.
- [7] Ali, A., Mehmood, A., (2008), Homotopy analysis of unsteady boundary layer flow adjacent to permeable stretching surface in a porous medium, Commun. Nonlinear Sci. Numer. Simul., 13, pp. 340-349.
- [8] Darvishi, M. T. and Khani, F., (2009), A series solution of the foam drainage equation, Computers and Mathematics with Applications, 58, pp. 360-368.
- [9] Patel, K. R., Mehta, M. N. and Patel, T. R., (2013), A mathematical model of imbibition phenomenon in heterogeneous porous media during secondary oil recovery process, Applied Mathematical Modelling, 37, pp. 2933-2942.
- [10] Parikh, A. K., Mehta, M. N. and Pradhan, V. H., (2014), Mathematical modeling and analysis of fingero-imbibition phenomenon in homogeneous porous medium with magnetic field effect in vertical downward direction, I. J. of Latest Tech. in Engg., Management & Appl. Sci., 3 (10), pp. 17-23.

- [11] Patel, A. V., Rabari, N. S. and Bhathawala, P. H., (2015), Numerical solution of imbibition phenomenon in a homogeneous medium with magnetic fluid, IOSR J. of Mathematics, 11(4), pp. 11-19.
- [12] Patel, M. A. and Desai, N. B., (2016), Homotopy analysis solution of countercurrent imbibition phenomenon in inclined homogeneous porous medium, Global J. Pure and Appl. Math., 12 (1), pp. 1035-1052.
- [13] Patel, M. A. and Desai, N. B., (2017), Homotopy analysis method for fingeroimbibition phenomenon in heterogeneous porous medium, Nonlinear Science Letters A: Math., Phy. and Mech., 8 (1), pp. 90-100.
- [14] Scheidegger, A. E., (1960), The Physics of flow through porous media, Revised edition, University of Toronto Press, Toronto.
- [15] Bear, J., (1972), Dynamics of fluids in porous media, American Elsevier Publishing Company, Inc., New York.
- [16] Liao, S. J., (2003), Beyond perturbation: Introduction to the homotopy analysis method, Chapman and Hall/CRC Press, Boca Raton.
- [17] Cheng, Z., (2007), Reservoir simulation: Mathematical techniques in oil recovery, Society for Industrial and Applied Mathematics, Philadelphia.
- [18] Liao, S. J., (2012), Homotopy analysis method in nonlinear differential equations, Higher Education Press, Beijing and Springer-Verlag Berlin Heidelberg.
- [19] Mehta, M. N., (1977), Asymptotic expansions of fluid flow through porous media, Ph.D. Thesis, South Gujarat University, Surat, India.
- [20] Liao, S. J., (1992), The proposed homotopy analysis technique for the solution of nonlinear problems, Ph.D. Thesis, Shanghai Jiao Tong University, Shanghai, China.
- [21] Desai, N. B., (2002), The study of problems arises in single phase and multiphase flow through porous media, Ph.D. Thesis, South Gujarat University, Surat, India.
- [22] Banerji, A. C. and Srivastava, K. M., (1963), Radial oscillations of variable magnetic star and the origin of the planetary system, Proceedings of the National Academy of Sciences, India, 33 (A), pp. 125-148.
- [23] Patel, M. A. and Desai, N. B., (2017), A mathematical model of cocurrent imbibition phenomenon in inclined homogeneous porous medium, Kalpa Publications in Computing, ICRISET2017, Selected Papers in Computing, 2, pp. 51-61.

Т	X = 0.1	X = 0.2	X = 0.3	X = 0.4	X = 0.5	X = 0.6	X = 0.7	X = 0.8	<i>X</i> = 0.9	X = 1.0
0.1	0.0294702	0.0409648	0.0548286	0.0714324	0.0911921	0.1145950	0.1422402	0.1749026	0.2136411	0.2600000
0.2	0.0528328	0.0676626	0.0848556	0.1048177	0.1280162	0.1550146	0.1865255	0.2235014	0.2672979	0.3200000
0.3	0.0759336	0.0938712	0.1141989	0.1373570	0.1638673	0.1943772	0.2297319	0.2711031	0.3202373	0.3800000
0.4	0.0987564	0.1195543	0.1427983	0.1689628	0.1986268	0.2325306	0.2716734	0.3174967	0.3722661	0.4400000
0.5	0.1212845	0.1446740	0.1705897	0.1995398	0.2321627	0.2692999	0.3121271	0.3624155	0.4231194	0.5000000
0.6	0.1435009	0.1691909	0.1975056	0.2289855	0.2643291	0.3044852	0.3508272	0.4055203	0.4724262	0.5600000
0.7	0.1653884	0.1930648	0.2234759	0.2571912	0.2949670	0.3378610	0.3874590	0.4463816	0.5196575	0.6200000
0.8	0.1869300	0.2162553	0.2484289	0.2840434	0.3239060	0.3691771	0.4216559	0.4844582	0.5640480	0.6800000
0.9	0.2081090	0.2387224	0.2722926	0.3094260	0.3509672	0.3981617	0.4529997	0.5190818	0.6044820	0.7400000
1.0	0.2289092	0.2604273	0.2949965	0.3332228	0.3759679	0.4245282	0.4810286	0.5494552	0.6393414	0.8000000

Table-1: Numerical values of the saturation of injected water with magnetic field effect.

 Table-2: Comparative numerical values of the saturation of injected water without magnetic field effect and with magnetic field effect.

Τ	X = 0.1	X = 0.2	X = 0.3	X = 0.4	X = 0.5	X = 0.6	X = 0.7	X = 0.8	<i>X</i> = 0.9	X = 1.0
0.1	0.0294301	0.0408938	0.0547358	0.0713267	0.0910823	0.1144897	0.1421481	0.1748322	0.2136012	0.2600000
0.1	0.0294702	0.0409648	0.0548286	0.0714324	0.0911921	0.1145950	0.1422402	0.1749026	0.2136411	0.2600000
0.2	0.0527940	0.0675937	0.0847656	0.1047151	0.1279096	0.1549123	0.1864359	0.2234330	0.2672591	0.3200000
0.2	0.0528328	0.0676626	0.0848556	0.1048177	0.1280162	0.1550146	0.1865255	0.2235014	0.2672979	0.3200000
0.3	0.0758961	0.0938046	0.1141118	0.1372578	0.1637642	0.1942783	0.2296453	0.2710369	0.3201998	0.3800000
0.3	0.0759336	0.0938712	0.1141989	0.1373570	0.1638673	0.1943772	0.2297319	0.2711031	0.3202373	0.3800000
0.4	0.0987202	0.1194901	0.1427143	0.1688671	0.1985275	0.2324355	0.2715902	0.3174333	0.3722302	0.4400000
0.4	0.0987564	0.1195543	0.1427983	0.1689628	0.1986268	0.2325306	0.2716734	0.3174967	0.3722661	0.4400000
0.5	0.1212496	0.1446122	0.1705089	0.1994478	0.2320674	0.2692088	0.3120477	0.3623551	0.4230855	0.5000000
0.5	0.1212845	0.1446740	0.1705897	0.1995398	0.2321627	0.2692999	0.3121271	0.3624155	0.4231194	0.5000000
0.6	0.1434674	0.1691316	0.1974281	0.2288975	0.2642381	0.3043985	0.3507520	0.4054637	0.4723946	0.5600000
0.6	0.1435009	0.1691909	0.1975056	0.2289855	0.2643291	0.3044852	0.3508272	0.4055203	0.4724262	0.5600000
0.7	0.1653563	0.1930080	0.2234018	0.2571073	0.2948806	0.3377792	0.3873886	0.4463291	0.5196290	0.6200000
0.7	0.1653884	0.1930648	0.2234759	0.2571912	0.2949670	0.3378610	0.3874590	0.4463816	0.5196575	0.6200000
0.8	0.1868992	0.2162010	0.2483583	0.2839637	0.3238244	0.3691004	0.4215907	0.4844107	0.5640233	0.6800000
0.8	0.1869300	0.2162553	0.2484289	0.2840434	0.3239060	0.3691771	0.4216559	0.4844582	0.5640480	0.6800000
0.9	0.2080794	0.2386705	0.2722254	0.3093505	0.3508905	0.3980903	0.4529401	0.5190399	0.6044621	0.7400000
0.9	0.2081090	0.2387224	0.2722926	0.3094260	0.3509672	0.3981617	0.4529997	0.5190818	0.6044820	0.7400000
1.0	0.2288809	0.2603777	0.2949326	0.3331515	0.3758960	0.4244623	0.4809749	0.5494194	0.6393273	0.8000000
1.0	0.2289092	0.2604273	0.2949965	0.3332228	0.3759679	0.4245282	0.4810286	0.5494552	0.6393414	0.8000000