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**SARDAR PATEL UNIVERSITY**  
**M.Sc. (Mathematics) Semester - II Examination**  
**Friday, 02<sup>nd</sup> November, 2018**  
**PS02EMTH04, Mathematical Classical Mechanics**

**Time: 10:00 a.m. to 01:00 p.m.**

**Maximum marks: 70**

Note: (1) Figures to the right indicate marks of the respective question.  
(2) Assume usual/standard notations wherever applicable.

Q-1 Choose the most appropriate option for each of the following questions.

[08]

1. If work done due to force  $\vec{F}$  does not depend on the path, then  $\vec{F}$  is \_\_\_\_\_.  
(a)  $\lambda V$                       (b)  $-\nabla \times V$                       (c) conservative                      (d) zero
2. For a system of particles center of mass \_\_\_\_\_.  
(a) is unique                      (c) does not exist  
(b) is stationary                      (d) is not unique
3. \_\_\_\_\_ gives the shortest distance between two particles in space.  
(a) Straight line                      (b) Catenary                      (c) Cycloid                      (d) Great circle
4. If Lagrangian does not depend on  $q$  explicitly, then \_\_\_\_\_ is conserved.  
(a)  $L$                       (b)  $\dot{q}$                       (c)  $p$                       (d)  $H$
5. Which of the following is incorrect?  
(a)  $\frac{\partial L}{\partial t} = -\frac{\partial H}{\partial t}$                       (b)  $\frac{\partial L}{\partial q_j} = -\frac{\partial H}{\partial q_j}$                       (c)  $\frac{\partial L}{\partial t} = -\frac{dh}{dt}$                       (d)  $\frac{\partial L}{\partial q_j} = \frac{\partial H}{\partial q_j}$
6. If  $q_j$  is cyclic in  $L$ , then it is \_\_\_\_\_ in  $H$ .  
(a) non-cyclic                      (b) ignorable                      (c) zero                      (d) constant
7.  $[q_2 + q_3, p_2] =$  \_\_\_\_\_; notation being usual.  
(a)  $-1$                       (b)  $1$                       (c)  $0$                       (d)  $2$
8. Lagrange bracket is \_\_\_\_\_.  
(a) constant                      (c) always non-vanishing  
(b) symmetric                      (d) a canonical invariant

Q-2 Attempt *any seven* of the following.

[14]

- (a) Define a non-holonomic constraint and give its example.
- (b) Define center of mass for a system of particles.
- (c) Define cyclic coordinate
- (d) State law of conservation of energy in Lagrangian formalism.
- (e) In usual notations, show that  $\frac{\partial H}{\partial t} = \frac{dH}{dt}$ .
- (f) State the principle of least action.
- (g) State the condition for a canonical transformation generated by a generating function of type  $F_2(q, P, t)$ .
- (h) Show that the transformation  $Q_i = p_i, P_i = -q_i$  is canonical.
- (i) Let  $H$  be Hamiltonian of a system. Show that if  $u(q, p, t)$  is a constant of motion, then  $\frac{\partial u}{\partial t} = [H, u]$ .

①

(P.T.O)

Q-3 (a) State Lagrange's equations of motion in general form. Hence derive Lagrange's equations of motion for a system when the forces are conservative and potential is independent of velocities. [06]

(b) Obtain Lagrange's equations of motion for a simple pendulum. [06]

OR

(b) For a system with  $n$ -degrees of freedom show that  $L' = L + \frac{dF}{dt}$  satisfies Lagrange's equations of motion, where  $L$  is Lagrangian of the system and  $F(q_1, q_2, \dots, q_n, t)$  is an arbitrary differentiable function of its arguments. [06]

Q-4 (a) State and prove the law of conservation of linear momentum in Lagrangian formalism. [06]

(b) Derive Euler's equation as the condition for extremum of the integral  $\int_{x_1}^{x_2} f(y, \dot{y}, x) dx$ . [06]

OR

(b) Lagrangian of a system is given by [06]

$$L = \frac{m}{2} (a\dot{x}^2 + 2b\dot{x}\dot{y} + c\dot{y}^2) - \frac{k}{2} (ax^2 + 2bxy + cy^2).$$

Evaluate the energy function and conjugate momenta. Which of them conserved? Justify.

Q-5 (a) State Hamilton's modified principle and derive Hamilton's equations of motion from it. [06]

(b) Derive Routhian equations of motion for a system with Lagrangian given by [06]

$$L = \frac{m}{2} (\dot{r}^2 + r^2\dot{\theta}^2) + \frac{k}{r}.$$

OR

(b) State Hamilton's equations of motion in matrix form and hence verify them for a system with degrees of freedom  $n = 3$ . [06]

Q-6 (a) Define a symplectic matrix. Show that the set of symplectic matrices forms a group under matrix multiplication. [06]

(b) Define canonical transformation. Show that the transformation [06]

$$Q_1 = q_1, \quad P_1 = p_1 - 2p_2, \quad Q_2 = p_2, \quad P_2 = -2q_1 - q_2.$$

is canonical.

OR

(b) Using Poisson brackets, show that no two components of angular momentum  $\bar{L}$  can simultaneously be chosen as canonical variables. [06]

