(48/A-24)

SEAT No.____

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SARDAR PATEL UNIVERSITY

B.Sc. (6th Semester) Examination Saturday, 31st March 2018 10:00 am to 01:00 pm

Electronics

US06CELE03- 8-bit Microprocessor programming and applications

0.				To	otal Marks : 70
	1 Multiple choice				[10]
1	instruction is used to increment the content of memory location by				
	one.				
_	(a) INR M	(b) ADD M	(c) DCR	. M	The state of the s
2		ator right instruction is			
_		(b) RRC		}	
3	a the conditional jump instruction.				
	(a) JNC	(b) JUMP 2050		(c) JUMP	The second of th
4.	. The stack is shar	ed by theand	the	·•	
	(a) CPU, Software (b) Programmer, Microprocessor				
	(c) Interpreter, (
5.	If Accumulator A equal to 59 H, after execution of ANI FO H the content of				
	accumulator is_				
		(b) 50 H			•
6.	Maximum time delay using single register program is				
	(a) 0.18 ms	(b) 18 ms	(c) 1.8	3 ms	man ne gragerie e ger
7.	To convert Binary number into BCD, if number is greater than 100, then Binary				
	number is subtra	cted by and	•		•
	(a) 100, 1	(b) 100, 10	כ	(c) 1000, 100	
8.		ASCII code is	•		e of extensioners typic grossy or
	(a) American Standard Code for Information Interfacing				
	(b) American Standard Code for Information Interchange				
	(c) American Standalone Code for Information Interchange				
9.	RET is byt			_	
	(a) 3	(b) 2	(c) 1		and the control of the three control of the control of the three control
10	. A Non- maskable	interrupt is known as _			
	(a) MNI	(b) NNI	(c) NMI		
ე .2	Answer any TEN (questions in brief			
1.	Define RAR and R	LC instructions			
		==			[P.T.O]

2. Define T states in microprocessor. 3. List the arithmetic instructions related to memory in 8085 microprocessor. 4. What is subroutine? To implement subroutine which instructions are required. 5. Define counter and time delay. 6. Draw the flow chart of time delay for two loops. 7. State different techniques of dynamic debugging. 8. Write down the subroutine to convert ASCII Hex code to Binary code. 9. Which instructions are used to store and retrieve data from stack? 10. How many ways we can reset the flip-flop in interrupt process? 11. Write instructions to enable all the interrupts in an 8085 microprocessor. 12. Define DAA instruction. Q.3 (a) Explain i) CMP R ii) CMP M iii) CPI 8-bit data. [07] (b) How microprocessor performs the compare instruction? [03] Q.3 (a) Explain Rotate instructions in detail. (b) State the applications of rotate instructions. [03] Q.4 (a) Write a program to count continuously in hexadecimal from FFH to 00H in a system with a 0.5 μs clock period. Use register C to set up a 1 ms delay between each count and display the numbers at one of the output port. (Given Count = 8C H) [05] (b) Write a program to count from 0 to 9 with a 1 sec delay between each count. At the count of 9, the counter should reset itself to 0 and repeat the sequence continuously. Use register pair HL to set up the delay and display each count at one of the output ports. (Given Count = A2C2 H) [05]Q.4 (a) Explain stack instructions in detail. [06] (b) Explain the similarities and differences between PUSH & POP with CALL & RETURN instructions. [04] Q.5 Write a main program and subroutines to convert BCD to seven segment LED CODE conversions. Write a program to convert BCD to Binary number. Q.5 [10] Q.6 Explain EI, DI, SIM, RIM instructions in detail. [10] Explain 8085 Vectored Interrupts. Q.6 [10]